1. First download Arduino IDE v1.8.12 and use the below library for CAN bus based communications.

[SeeedStudio CAN BUS](https://github.com/Seeed-Studio/Seeed_Arduino_CAN/tree/old)

Go to Seeed-Studio ( Github repo) 🡺 Seeed\_Arduino\_CAN 🡺 select old branch

Also we need to add libraries for sensors , which will later be discussed.

1. We will have to add Seeeduino Xiao , so go to this [seeeduino xiao](https://wiki.seeedstudio.com/Seeeduino-XIAO/) link and see **getting started** topic to add xiao to your Arduino board manager
2. We will have to add Blue Pill to our board manager. This link [BluePill](https://www.electronicshub.org/getting-started-with-stm32f103c8t6-blue-pill/) demonstrates how to use bluepill board. Also for Blue Pill we need a CAN library and hence use [exocan](https://github.com/exothink/eXoCAN) , the following link to add CAN to your bluepill board.